

On Reciprocity in Linear Time-Invariant Networks

By

B. D. O. ANDERSON,
(Associate Member)

and

R. W. NEWCOMB
(non-member)*

Summary.—A general time-domain definition of reciprocity is given in terms of network-port variables, and this definition is applied to conclude the symmetry of network matrices, even in the case of active, nonfinite networks. A new proof is presented of the reciprocity of finite networks composed of time-invariant resistors, capacitors, inductors and transformers, and this proof is also applied to show the reciprocity of interconnections of a wide class of reciprocal networks.

1.—Introduction.

We first consider a general definition of reciprocity for linear time-invariant networks and from this deduce certain equivalent definitions which depend on additional assumptions being made, such as the existence of an impedance matrix. The initial definition is a time-domain one; the property of reciprocity of a network is independent of whether or not the network inputs are Laplace-transformable, and to discuss reciprocity (as is often done) with inputs being restricted to being Laplace-transformable is therefore better avoided if possible.

The time-domain definition is initially in terms of voltage and current variables. An equivalent definition in terms of scattering variables (incident and reflected voltage waves) is given. This allows the effect the reciprocity constraint has on the scattering matrix, when this matrix exists, to be examined. Here, as in the immittance matrix case, it is concluded that symmetry of the matrix is a consequence of reciprocity.

The third section of the paper considers primarily the case of networks composed of a finite number of positive-valued (passive) resistors, capacitors and inductors, together with multiport transformers. The scattering matrix (though not the impedance matrix) for such a network always exists (Ref. 1), and the matrix is shown to be symmetric. The method used to prove this result is based on a representation of the network as a "cascade loading" (Ref. 1), that is, the cascade connection of a network consisting entirely of opens and shorts, and a loading network that is a multiport of uncoupled resistors, capacitors, inductors, and transformers. Finally, it is shown that any interconnection of linear, passive, solvable, reciprocal time-invariant networks is again a reciprocal network.

2.—Reciprocity for Linear Time-Invariant Networks.

As explained in the introductory section, we are interested in defining reciprocity in the widest possible sense, that is, assuming linearity and time-invariance but as little else as possible. Definitions requiring, for example, that a unit impulse of current at port i gives a voltage at port j which is the same as the voltage at port i produced by a unit impulse of current at port j are unnecessarily restrictive. This particular definition requires the existence of an impedance matrix, and, as such, does not even apply to a network consisting of a simple transformer.

We offer what we believe to be the most general definition, put in the terms of earlier discussions of network definitions (Refs. 2 and 3).

We assume that an n -port network N permits voltage-current pairs $[v, i]$ (termed allowed pairs) at its terminals, where v, i are

real-valued n -vector functions of time, zero up until some finite time, and infinitely differentiable after this time. The physical reasoning behind these assumptions may be found in Refs. 2 and 3. We shall write $v \in \mathcal{D}_+$ to signify that v has these properties.

Suppose $[v_1, i_1]$ and $[v_2, i_2]$ are two arbitrary allowed pairs. Then by definition N is reciprocal if for all such choices

$$\tilde{v}_1 * i_2 = \tilde{v}_2 * i_1 \dots\dots\dots(1)$$

The symbol $*$ denotes convolution; the superscript tilde \sim denotes matrix transposition.

If $v_1 = [v_{1\alpha}], i_2 = [i_{2\alpha}]$ etc., Eq. (1) written in full becomes

$$\sum_{\alpha=1}^n \int_{-\infty}^{+\infty} v_{1\alpha}(t - \tau) i_{2\alpha}(\tau) d\tau = \sum_{\alpha=1}^n \int_{-\infty}^{+\infty} v_{2\alpha}(t - \tau) i_{1\alpha}(\tau) d\tau \dots\dots(1')$$

Definition 1, which appears elsewhere (Ref. 2 and Ref. 4, p. 236), has been termed Lorentz reciprocity, as it is suggested by a theorem originally stated by Lorentz for electromagnetic systems. We comment further that since the various functions involved in Eq. (1) are zero up until some finite time the convolutions are well defined, and the convolution product is commutative.

In preparation for dealing with networks possessing a scattering matrix, we introduce at this stage scattering variables v^i, v^r (incident and reflected voltage vectors) for the network N (Ref. 5, p. 142). These quantities are defined through

$$2v^i = v + i \dots\dots\dots(2a)$$

$$2v^r = v - i \dots\dots\dots(2b)$$

Note that by defining scattering variables we are not predicating the existence of a scattering matrix. Corresponding to allowed pairs $[v_1, i_1]$ and $[v_2, i_2]$ we have pairs $\{v_1^i, v_1^r\}$ and $\{v_2^i, v_2^r\}$, where the different brackets are to distinguish scattering variables from the ordinary variables.

Then we claim that an alternate statement of reciprocity is: N is reciprocal if for arbitrary allowed $\{v_1^i, v_1^r\}$ and $\{v_2^i, v_2^r\}$

$$\tilde{v}_1^i * v_2^r = \tilde{v}_2^i * v_1^r \dots\dots\dots(3)$$

Eqs. (1) and (3) are strictly equivalent, so that Eq. (3) could, equally well, be taken as the reciprocity definition. To see for example that Eq. (3) implies Eq. (1), substitute for the variables v_1^i etc. in Eq. (3) by using Eq. (2). On cancelling out like terms on each side of the resulting equation, Eq. (1) follows. In an equally simple fashion Eq. (3) follows from Eq. (1).

Let us now specialize N so that it is linear, time-invariant and completely solvable, that is, N possesses a (time-domain) scattering matrix (Ref. 6). The class of networks possessing scattering matrices is a more general one than the class possessing impedance matrices (Ref. 7, p. 122) for example, any finite linear time-invariant N composed of standard passive-network elements which possesses an impedance matrix also possesses a scattering matrix,

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The authors are, respectively, Professor of Electrical Engineering, University of Newcastle, and Associate Professor, Stanford Electronics Laboratories, Stanford University, Stanford, California.

not vice versa (Ref. 1). Accordingly we choose first to make specialization, rather than assume the existence of an immittance matrix. The time-domain scattering matrix is used as this is a more fundamental matrix than the more common frequency-domain matrix, which exists if and only if the time-domain matrix is Laplace-transformable.

Since any physical network N (active or passive) is non-anti-passive, we shall assume that the scattering matrix $s \equiv s(t)$ is causal for $t < 0$, and maps incident voltages into reflected voltages through

$$v^r = s * v^i \quad \dots\dots\dots(4)$$

where $v^i \in \mathcal{D}_+$ but is otherwise arbitrary. If all quantities are Laplace-transformable, then Eq. (4) implies the more familiar relation $V^r(p) = S(p) V^i(p)$.

In general s will not be a function; however, it is shown in Ref. 6 that s will be a distribution in the variable t (Ref. 8), typically involving a delta function and a unit step function. Because s is causally zero for negative values of the argument s is said to be in the space \mathcal{D}'_+ (Ref. 9, p. 28) of distributions with support bounded on the left. The variables v^r and v^i being in the space \mathcal{D}_+ are also in the space \mathcal{D}'_+ .

Substituting from Eq. (4) into Eq. (3) we have

$$\tilde{v}_1^i * (s * v_2^i) = \tilde{v}_2^i * (s * v_1^i) \quad \dots\dots\dots(5a)$$

Theorem of L. Schwartz (Ref. 9, p. 28) shows that the convolution products in this equation are associative and commutative since various factors are all in the space \mathcal{D}'_+ . Accordingly,

$$\begin{aligned} \tilde{v}_1^i * s * v_2^i &= \tilde{v}_2^i * s * v_1^i \\ &= \tilde{v}_1^i * \tilde{s} * v_2^i \quad \dots\dots\dots(5b) \end{aligned}$$

We may choose v_1^i and v_2^i arbitrarily; take in particular v_1^i to have all entries zero except the k -th, and v_2^i to have all entries zero except the l -th. The non-zero entries of v_1^i and v_2^i are arbitrary \mathcal{D}_+ functions. Then

$$v_{1k}^i * s_{kl} * v_{2l}^i = v_{2l}^i * s_{lk} * v_{1k}^i \quad \dots\dots\dots(6)$$

which implies that

$$s_{kl} = s_{lk} \quad \dots\dots\dots(7)$$

Conversely also that Eq. (7) implies Eq. (5a). This yields the following theorem.

Theorem 1:
A linear time-invariant completely solvable network N is reciprocal if and only if its (time-domain) scattering matrix is symmetric.

In the case where the Laplace transform $\mathcal{L}[s(t)] = S(p)$ exists and is causal

Corollary:
A linear time-invariant solvable network N possessing a scattering matrix $S(p)$ is reciprocal if and only if $S(p)$ is symmetric.

We comment that the preceding proof does not assume the existence of $\mathcal{L}[s]$, $\mathcal{L}[v^i]$, $\mathcal{L}[v^r]$, and is, accordingly, more general than any proof considering all quantities to be defined in the (common) frequency domain. It should also be noted that the result is independent of the passivity (or lack of it) of the network N . Neither N nor N have to be finite.

What now of the linear time-invariant network which possesses an impedance matrix $z(t)$, with possibly $Z(p)$ existing as well? Arguments similar to those used to establish Theorem 1, but starting from Eq. (1) rather than Eq. (3) yield:

Theorem 2:
A linear time-invariant network N possessing an impedance matrix $z(t)$ (and perhaps $Z(p)$) is reciprocal if and only if $z(t)$ (and $Z(p)$) is symmetric.

A similar theorem holds of course for admittance matrices.

Note that if $S(p)$ and $Z(p)$ both exist, then the symmetry of one follows immediately from the symmetry of the other through the equations (Ref. 10, p. 242)

$$S(p) = [Z(p) + 1]^{-1} [Z(p) - 1] \quad \dots\dots\dots(8a)$$

$$Z(p) = [1 - S(p)]^{-1} [1 + S(p)] \quad \dots\dots\dots(8b)$$

3.—Reciprocity for Finite Passive Linear Time-Invariant Networks and Interconnections of Reciprocal Networks.

In this section we consider networks composed of a finite number of positive resistors, capacitors, inductors, and multiport transformers, that is, the most general kind of linear, passive, finite time-invariant network composed of reciprocal elements. The reciprocity of such a network was established by McMillan (Ref. 4), and more recently for example by de Buda (Ref. 11). We present here a simple proof relying on the result established elsewhere (Ref. 1) that the scattering matrix of such a network exists in the complex frequency domain (p -domain), and further apply this result to the interconnections of passive reciprocal networks.

It is clear, and shown in Ref. 1, that any finite linear time-invariant n -port network N composed of positive resistors, capacitors and inductors, together with multiport transformers, can be represented as the cascade connection of a network N_Σ composed entirely of opens and shorts, terminated in a network N_f consisting of all the resistors, capacitors, etc., of N unconnected to each other. This is shown in Fig. 1.

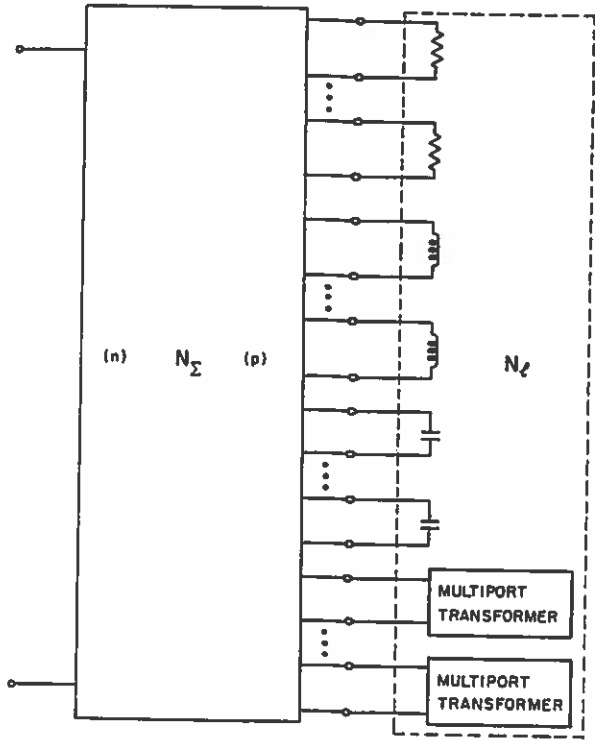


Fig. 1.—Cascade Loading Representation of N .

A multiport transformer may be described by the equations

$$v_1 = \tilde{T} v_2 \quad \dots\dots\dots(9a)$$

$$i_2 = -T i_1 \quad \dots\dots\dots(9b)$$

where T is a constant $m \times n$ matrix, the transformer having n primary and m secondary ports. The vectors v_1, v_2 are the primary and secondary voltages, and i_1, i_2 the primary and secondary currents. The transformer has the scattering matrix

$$S(p) = \begin{bmatrix} (1_n + \tilde{T}T)^{-1}(\tilde{T}T - 1_n) & 2(1_n + \tilde{T}T)^{-1}\tilde{T} \\ 2T(1_n + \tilde{T}T)^{-1} & (1_m + T\tilde{T})^{-1}(1_m - T\tilde{T}) \end{bmatrix} \quad \dots\dots\dots(10)$$

which is easily verified to be symmetric. As a consequence, N_z as a symmetric scattering matrix Σ and is therefore reciprocal, since, as is shown in Ref. 1, N_z is subject to the same constraining relations as a multiport transformer. The network N_i also has a symmetric scattering matrix S_i , this being the (matrix) direct sum of a number of symmetric matrices (corresponding to each of the network elements of N_i , each of which is reciprocal).

We partition Σ as

$$\Sigma = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix} = \tilde{\Sigma}$$

where Σ_{11} is $n \times n$, corresponding to the input ports of N_i , Σ_{22} is $p \times p$, where N_i has p ports.

The scattering matrix S of the cascade loading interconnection may be evaluated using methods outlined in Ref. 12 as

$$S = \Sigma_{11} + \Sigma_{12} S_i (1_p - \Sigma_{22} S_i)^{-1} \Sigma_{21} \dots \dots \dots (11a)$$

or equivalently

$$S = \Sigma_{11} + \Sigma_{12} (1_p - S_i \Sigma_{22})^{-1} S_i \Sigma_{21} \dots \dots \dots (11b)$$

Difficulties arise due to the question of the existence of the inverse of $(1_p - \Sigma_{22} S_i)$ or $(1_p - S_i \Sigma_{22})$ and are dealt with in the Appendix. Here we shall simply assume the inverses exist. Taking the transpose of Eq. (11a):

$$\tilde{S} = \tilde{\Sigma}_{11} + \tilde{\Sigma}_{12} (1_p - \tilde{S}_i \tilde{\Sigma}_{22})^{-1} \tilde{S}_i \tilde{\Sigma}_{21}$$

Using the symmetry of Σ and S_i ,

$$\tilde{S} = \Sigma_{11} + \Sigma_{12} (1_p - S_i \Sigma_{22})^{-1} S_i \Sigma_{21}$$

Using Eq. (11b) it follows that

$$S = \tilde{S} \dots \dots \dots (12)$$

By the corollary to Theorem 1, this implies that the network N is reciprocal. Hence we have the following statement.

Theorem 3:

A network consisting of a finite number of passive time-invariant resistors, capacitors, inductors and multiport transformers, is reciprocal, and in fact possesses a symmetric scattering matrix.

This result is capable of almost immediate generalization. Suppose N_1 and N_2 are any two linear, passive, time-invariant reciprocal networks possessing scattering matrices $S_1(p)$ and $S_2(p)$ and that N_1 and N_2 are connected together in some arbitrary fashion. As before, we represent the interconnecting network as N_z with scattering matrix Σ , and the load network as N_i , consisting of N_1 and N_2 uncoupled networks (see Fig. 2). The network N_i is of course linear, passive, time-invariant and reciprocal, and possesses a scattering matrix equal to the direct sum of $S_1(p)$ and $S_2(p)$. The arguments used to establish Theorem 3 depend merely on the passivity and symmetry of the matrices involved rather than, for example, the fact that these matrices are derived from finite networks, and accordingly they carry through to show:

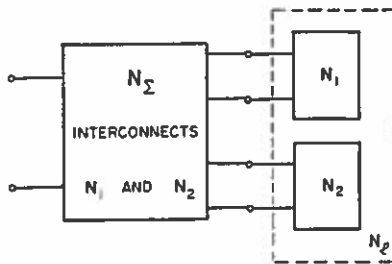


Fig. 2.—General Interconnection of Two Reciprocal Networks.

Theorem 4:

Let N_1 and N_2 be two linear, passive, time-invariant reciprocal networks possessing scattering matrices $S_1(p)$ and $S_2(p)$. Then any arbitrary interconnection of N_1 and N_2 is also reciprocal, and in fact possesses a symmetric scattering matrix $S(p)$.

Conclusions.

Reciprocity is a meaningful concept for linear time-invariant networks; existence of impedance matrices or Laplace-transformable inputs are not necessary prerequisites for a discussion of reciprocity. A time-domain definition of reciprocity which encompasses the more common but less general definitions usually given is considered, and an equivalent statement in terms of the often more useful scattering variables is given. The symmetry of network matrices when they exist is implied by reciprocity, and this property is independent of properties such as network passivity. A new proof is given of the reciprocity of finite passive resistor, capacitor, inductor, transformer networks which is an application of earlier work (Ref. 1). This proof is independent of the existence of chain or impedance matrices.

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APPENDIX.

Suppose $(1_p - \Sigma_{22} S_i)^{-1}$ does not exist. Now, as is pointed out in Ref. 1 $\begin{bmatrix} \Sigma_{11} & \Sigma_{12} S_i \\ \Sigma_{21} & \Sigma_{22} S_i \end{bmatrix}$ and $\Sigma_{22} S_i$ are passive scattering matrices, and accordingly (Ref. 7, p. 121), there exists a constant orthogonal matrix T such that

$$\begin{bmatrix} 1 & 0 \\ 0 & \tilde{T} \end{bmatrix} \begin{bmatrix} \Sigma_{11} & \Sigma_{12} S_i \\ \Sigma_{21} & \Sigma_{22} S_i \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & T \end{bmatrix} = \begin{bmatrix} \Sigma_{11} & \hat{\Sigma}_{12} & 0 \\ \hat{\Sigma}_{21} & \hat{\Sigma}_{22} & 0 \\ 0 & 0 & 1_p \end{bmatrix}$$

with $\tilde{T} \Sigma_{21} = \begin{bmatrix} \hat{\Sigma}_{21} \\ 0 \end{bmatrix}$, $\Sigma_{12} S_1 T = [\hat{\Sigma}_{12} \ 0]$ and $\det(1_{p-r} - \hat{\Sigma}_{22}) \neq 0$,

that is $(1_{p-r} - \hat{\Sigma}_{22})^{-1}$ exists. Range space arguments following those given in Ref. 1 then show that in place of

$$S = \Sigma_{11} + \Sigma_{12} S_1 (1_p - \Sigma_{22} S_1)^{-1} \Sigma_{21} \dots \dots \dots (11a)$$

or equivalently

$$\begin{aligned} S &= \Sigma_{11} + \Sigma_{12} S_1 T \{ \tilde{T} (1_p - \Sigma_{22} S_1) T \}^{-1} \tilde{T} \Sigma_{21} \\ &= \Sigma_{11} + [\hat{\Sigma}_{12} \ 0] \begin{bmatrix} (1_{p-r} - \hat{\Sigma}_{22}) & 0 \\ 0 & 0 \end{bmatrix}^{-1} \begin{bmatrix} \hat{\Sigma}_{21} \\ 0 \end{bmatrix} \end{aligned}$$

we have

In place of $S = \Sigma_{11} + \hat{\Sigma}_{12} (1_{p-r} - \hat{\Sigma}_{22})^{-1} \hat{\Sigma}_{21} \dots \dots \dots (13a)$

$$S = \Sigma_{11} + \Sigma_{12} (1_p - S_1 \Sigma_{22})^{-1} S_1 \Sigma_{21} \dots \dots \dots (11b)$$

or equivalently

$$\begin{aligned} S &= \Sigma_{11} + \tilde{\Sigma}_{21} (1_p - \Sigma_{22} S_1)^{-1} \tilde{S}_1 \tilde{\Sigma}_{12} \\ &= \Sigma_{11} + \tilde{\Sigma}_{21} T \{ \tilde{T} (1_p - \Sigma_{22} S_1) T \}^{-1} \tilde{T} \tilde{S}_1 \tilde{\Sigma}_{12} \\ &= \Sigma_{11} + [\hat{\Sigma}_{21} \ 0] \begin{bmatrix} (1_{p-r} - \hat{\Sigma}_{22}) & 0 \\ 0 & 0 \end{bmatrix}^{-1} \begin{bmatrix} \tilde{\Sigma}_{12} \\ 0 \end{bmatrix} \end{aligned}$$

we have

$$S = \Sigma_{11} + \hat{\Sigma}_{21} (1_{p-r} - \hat{\Sigma}_{22})^{-1} \hat{\Sigma}_{12} \dots \dots \dots (13b)$$

From Eqs. (13a) and (13b) we conclude that

$$S = \tilde{S} \dots \dots \dots (12)$$

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