Types of Beam Structure	Connection to Mechanics	Relationship between Shear Force and Bending Moment	Examples
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Analysis of Beam Structures

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Overview			

- 1 Types of Beam Structure
- 2 Connection to Mechanics

3 Relationship between Shear Force and Bending Moment

- Mathematical Preliminaries
- Derivation of Equations





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Types of Beam Structures

Simply Supported Beam:



Cantilever:



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Types of Beam Structures

Supported Cantilever:



Fixed-Fixed Beam Structure:



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Types of Beam Structures

Boundary Conditions

Simply Supported Beam

• y(0) = y(L) = 0.

Cantilever Beam

•
$$y(0) = 0, \frac{dy}{dx}|_{x=0} = 0$$

Supported Cantilever Beam

•
$$y(0) = y(L) = 0, \ \frac{dy}{dx}|_{x=0} = 0$$

Fixed-Fixed Beam

•
$$y(0) = y(L) = 0, \ \frac{dy}{dx}|_{x=0} = \frac{dy}{dx}|_{x=L} = 0$$



Q1. What is the relationship between inputs and outputs?



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Decisions will be based on estimates of outputs.



Typical problem: Given input parameters, compute y(x), find location and magnitude of y_{min} and y_{max} .



For simple problems, can rely on intuition. Otherwise, need math and mechanics.



Q2. What is the relationship among the outputs? Are they dependent?



We will need to work with a chain of dependencies.

Q3. What is the relationship between V(x) and M(x)? Are they independent? No! We will see: $V(x) = \frac{dM(x)}{dx}$, but not always true!

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Problem Setup



Stress-Strain Relationships



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For design purposes we need to make sure:

$$\sigma_{tension} < \sigma_{max}$$
 tension (1)

and

$$\sigma_{compression} < \sigma_{max}$$
 compression (2)

Also,

$$\epsilon_{\max \text{ compression}} \le \epsilon(y) \le \epsilon_{\max \text{ tension}}$$
 (3)

These constraints limit the amount of load that a beam can carry.

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Section-Level Behavior

From a design standpoint we can reduce $\sigma(y)$ and $\epsilon(y)$ by increasing the moment of interia in

$$\sigma(y) = \left[\frac{My}{l}\right].$$
 (4)

To maximise I, maximize distance of material from neutral axis.





Good Choice of Inertia



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Assumptions. We will assume beam length / depth \gg 10.

Therefore, displacements will be dominated by flexural bending.



Sections remain perpendicular to the deformed neutral axis.

This is not the case for shear deformations.

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Relationship between Shear Force and Bending Moment

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Relationship between Shear Force and Bending Moment

Basic Questions

- Are V(x) and M(x) independent? No!
- Under what conditions does a dependency relationship exist?

Strategy

- Introduce relavant mathematics.
- Extract a thin section from a beam and examine its equilibrium.
- See where the mechanics takes us!

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Mathematical Preliminaries

Taylor Series Expansion. Let y = f(x) be a smooth differentiable function.



Given f(x) and derivatives f'(a), f''(a), f'''(a), etc, the purpose of Taylor's series is to estimate f(x + h) at some distance h from x.

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Mathematical Preliminaries

The Taylor series is as follows:

$$f(x+h) = \sum_{k=0}^{\infty} \frac{f^{k}(x)}{k!} h^{k} = f(x) + f'(x)h + \frac{f''(x)}{2!}h^{2} + \frac{f'''(x)}{3!}h^{3} + \cdots$$
(5)

For a Taylor series approximation containing (n + 1) terms

$$f(x+h) = \sum_{k=0}^{k=n} \frac{f^k(x)}{k!} h^n + O(h^{(n+1)})$$
(6)

The big-O notation indicates how quickly the error will change as a function of h, e.g., $O(h^2) \rightarrow magnitude$ of error proportional to h squared.

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Mathematical Preliminaries

Finite Difference Derivatives. Truncating equation 6 after two terms gives:

$$f(x+h) = f(x) + f'(x)h + O(h^2).$$
 (7)

A simple rearrangement of equation 7 gives:

$$\frac{dy}{dx} = \lim_{h \to 0} \left[\frac{f(x+h) - f(x)}{h} \right].$$
 (8)

Similarly, we require:

$$\frac{dy}{dx} = \lim_{h \to 0} \left[\frac{f(x) - f(x - h)}{h} \right].$$
(9)

In order for the derivative to exist, equations 8 and 9 need to be the same!

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Mathematical Preliminaries

Simple Example. Let $y = x^2$.

$$\frac{dy}{dx} = \lim_{h \to 0} \left[\frac{(x+h)^2 - x^2}{h} \right] = \lim_{h \to 0} [2x+h] = 2x.$$
(10)

Home Exercise. Use first principles to find dy/dx when:

$$y(x) = (x^2 - 4x + 3)^2$$
 (11)

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Counter Example. y(x) = |x| is not differentiable at x = 0.

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Test Problem for Derivation of Equations



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 Observation of Equations
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Part 1: Equilibrium in Vertical Direction:

$$\sum F_{y} = 0 \; \to \; V(x) - V(x + dx) - w(x)dx = 0 \qquad (12)$$

From the Taylors series expansion:

$$V(x+dx) = V(x) + \frac{dV}{dx}dx + O(dx^2)$$
(13)

Plugging equation 13 into 12 and ignoring higher-order terms:

$$\sum F_{y} = 0 \rightarrow V(x) - \left[V(x) + \frac{dV}{dx}dx\right] - w(x)dx = 0 \quad (14)$$

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Derivation of Equations

Hence,

$$\frac{dV}{dx} + w(x) = 0 \leftarrow \text{gradient of shear force equals -}w(x). \quad (15)$$

Part 2: $\sum M_o = 0$ (anticlockwise +ve)

$$-V(x)dx - M(x) + M(x + dx) + w(x)dx \cdot \frac{dx}{2} = 0$$
 (16)

Note:

- The term w(x)dx is the vertical load acting on the element.
- The term dx/2 is the distance from O to the centroid of loading.

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Derivation of Equations

From the Taylor Series expansion:

$$M(x + dx) = M(x) + \frac{dM}{dx}dx + O(dx^2)$$
(17)

Plugging equation 17 into 16 and ignoring terms $O(dx^2)$ and higher:

$$V(x) = \frac{dM}{dx} \leftarrow \text{shear force} = \text{gradient of bending moment.}$$
 (18)

Note. Equation 18 only applies when the derivatives of M(x) with respect to x exist.

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Derivation of Equations

Illustrative Example



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Shear Force and Bending Moment

Interpretation. Consider an interval [a, b] on a beam:

$$dV = -w(x)dx \rightarrow \int_{a}^{b} dV = -\int_{a}^{b} w(x)dx = V(b) - V(a).$$
 (19)

Key Point: Change in shear force between points a and b = total loading within interval.

$$dM = V(x)dx \rightarrow \int_a^b dM = \int_a^b V(x)dx = M(b) - M(a). \quad (20)$$

Key Point: Change in moment between points a and b = area under the shear force diagram.

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Shear Force and Bending Moment

Example 1.



Check Shear Loading (a = 0, b = L):

$$V(b) - V(a) = V(L) - V(o) = -wL = -\int_0^L w_o dx.$$
 (21)

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Shear Force and Bending Moment

Check Relationship between Shear and Bending Moment:

$$V(x) = \frac{dM(x)}{dx} = w_o(L - x).$$
⁽²²⁾

For a = 0 and b = L we expect:

$$\int_0^L V(x) dx = w_o \int_0^L () dx = M(L) - M(0).$$
 (23)

For a general value x:

$$M(x) = w_o \int_x^L (L-s) ds = w_o L x - \frac{1}{2} w_o x^2 + A.$$
 (24)

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Shear Force and Bending Moment

Apply Boundary Conditions:

$$M(L) = 0 \to A = -\frac{1}{2}wL^2.$$
 (25)

Hence,

$$M(x) = wLx - \frac{1}{2}wx^2 - \frac{1}{2}wL^2 = -\frac{1}{2}w(L-x)^2.$$
 (26)

Check Moment at Boundary Conditions:

•
$$M(L) = wL^2 - \frac{1}{2}2wL^2 = 0. \checkmark$$

• $M(0) = -\frac{1}{2}wL^2. \checkmark$

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Shear Force and Bending Moment

Physical Interpretation

For the extracted element:

$$\sum F_{y}(x) = 0 \to V(x) = w_{o}(L - x).$$
 (27)

Similarly,



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Shear Force and Bending Moment Diagrams



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Shear Force and Bending Moment

Example 2.



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Relationship between Shear Force and Bending Moment

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Shear Force and Bending Moment

Bending Moment at x = L/2 (extract substructure):



Taking moments:

$$M(L/2) = \underbrace{\frac{w_o L}{2}}_{reaction} \frac{L}{2} - \underbrace{\frac{w_o L}{2}}_{loading \ centroid} \underbrace{\frac{L}{4}}_{entroid} = \frac{w_o L^2}{8}.$$
 (29)

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Shear Force and Bending Moment

Equation for M(x)?

We have:

- Axis of symmetry at x = L/2.
- M(x) will have roots at x = 0 and x = L.

Hence, let M(x) = Ax(x - L), then use midpoint moment to determine A:

$$M(L/2) = A \frac{L}{2} \left(\frac{-L}{2} \right) - > A = -\frac{w_o}{2}.$$
 (30)

Thus,

$$M(x) = \frac{w_o}{2} x (L - x).$$
 (31)

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Shear Force and Bending Moment

Example 3.

